

# Lightweight MDS Serial-type Matrices with Minimal Fixed XOR Count

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# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

# Diffusion Matrices

The diffusion layer of a cipher (often expressed as a diffusion matrix) plays the role of diffusion:

spread the internal dependencies.

The diffusion matrix  $\mathbf{M}$  of order  $k$  is applied to a  $k$ -tuple input vector  $\mathbf{u}$  to create the diffusion.

Its diffusion power can be quantified by the branch number of a matrix.

$$\mathcal{B}(\mathbf{M}) = \min_{\mathbf{u} \neq \mathbf{0}} (wt(\mathbf{u}) + wt(\mathbf{M}\mathbf{u})),$$

where  $wt(\cdot)$  is the number of non-zero components in the vector.

# Maximal Distance Separable (MDS) Matrices

## Definition (MDS)

An MDS matrix  $\mathbf{M}$  of order  $k$  is a diffusion matrix with optimal branch number  $k + 1$ . I.e.  $\mathcal{B}(\mathbf{M}) = k + 1$ .

## Definition ( $q$ -MDS)

A  $q$ -MDS matrix  $\mathbf{M}$  of order  $k$  is a diffusion matrix with optimal branch number  $k + 1$  when raised to its  $q$ -th power.

I.e.  $\mathcal{B}(\mathbf{M}^q) = k + 1$

$q$ -MDS matrix is also called recursive MDS matrix.

# Hardware Implementation of Diffusion Matrices

Let  $\mathcal{C}(\mathbf{M})$  and  $\mathcal{C}(\alpha)$  be the number of XOR gates needed to implement a matrix and its coefficient respectively.

## Example

The AES diffusion matrix  $\mathbf{M}_A$  (over  $\text{GF}(2^8)$ ).

$$\begin{pmatrix} 2 & 3 & 1 & 1 \\ 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 3 \\ 3 & 1 & 1 & 2 \end{pmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 2a \oplus 3b \oplus c \oplus d \\ a \oplus 2b \oplus 3c \oplus d \\ a \oplus b \oplus 2c \oplus 3d \\ 3a \oplus b \oplus c \oplus 2d \end{bmatrix}$$

The implementation cost  $\mathcal{C}(\mathbf{M}_A) = 4 \cdot (\mathcal{C}(2) + \mathcal{C}(3)) + 4 \cdot 3 \cdot 8$ .

These two terms are called the **variable cost** and the **fixed cost** respectively.

## Fixed Cost of MDS matrices

### Proposition

*All coefficients of an MDS matrix are non-zero.*

Thus, the fixed cost of an MDS matrix of order  $k$  over  $\text{GF}(2^s)$  is

$$k \cdot (k - 1) \cdot s$$

One research direction considers the serial-type matrices that are  $q$ -MDS to have an **area/clock cycle trade-off to achieve lower fixed cost.**

# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4



# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

# Linear Feedback Serial (LFS) Matrices

An example of serial-type matrices is the serial matrices (for clarity purposes, we call them LFS matrices) that is used in the family of hash functions PHOTON [GP+11].

## Definition

An LFS matrix  $\mathbf{L} = LFS(z_0, z_1, \dots, z_{k-1})$  of order  $k$  is a matrix of the following form:

$$\mathbf{L}_{ij} = \begin{cases} z_j, & i = k - 1 \\ 1, & i + 1 = j \\ 0, & \text{otherwise.} \end{cases} \quad \text{e.g.} \quad \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ z_0 & z_1 & z_2 & z_3 \end{pmatrix}$$

## Area/Clock Cycle Trade-off

## Example

Let  $\mathbf{L}_4 = LFS(z_0, z_1, z_2, z_3)$  be a diffusion matrix over  $GF(2^8)$ .

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ z_0 & z_1 & z_2 & z_3 \end{pmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} b \\ c \\ d \\ z_0 a \oplus z_1 b \oplus z_2 c \oplus z_3 d \end{bmatrix}$$

The implementation cost  $\mathcal{C}(\mathbf{L}_4) = \sum \mathcal{C}(z_i) + 3 \cdot 8$ .

Suppose  $\mathbf{L}_4$  is 4-MDS, one can implement (costs about  $\frac{1}{4}$  of MDS matrices) and reuse the circuit to update the input vector 4 times (4 clock cycles) to achieve the MDS property.

## Fixed Cost of LFS matrices

### Theorem

*If an LFS matrix of order  $k$  is  $k$ -MDS, then  $z_i \neq 0$  for all  $i$ .*

Thus, the fixed cost of a  $k$ -MDS LFS matrix of order  $k$  over  $\text{GF}(2^s)$  is

$$(k - 1) \cdot s$$

Can we achieve even lower fixed cost?

# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

# Diagonal-Serial Invertible (DSI) Matrices

We propose a new serial-type matrix:

## Definition

A DSI matrix  $\mathbf{D}$  of order  $k$  is determined by 2 vectors,  $\mathbf{a} = (a_1, a_2, \dots, a_{k-1}, a_k)$ , where  $a_i$ 's are non-zero, and  $\mathbf{b} = (b_1, b_2, \dots, b_{k-1})$ , as follows:

$$D_{ij} = \begin{cases} a_1, & i = 1, j = k \\ a_i, & i = j + 1 \\ b_i, & i = j \leq k - 1 \\ 0, & \text{otherwise.} \end{cases} \quad \text{e.g.} \quad \begin{pmatrix} b_1 & 0 & 0 & a_1 \\ a_2 & b_2 & 0 & 0 \\ 0 & a_3 & b_3 & 0 \\ 0 & 0 & a_4 & 0 \end{pmatrix}$$

## Theorem

Every DSI matrix  $\mathbf{D} = \text{DSI}(\mathbf{a}, \mathbf{b})$  is invertible.

# Sparse DSI Matrices

## Definition

A DSI matrix  $\mathbf{D}$  of order  $k$  is **sparse** if  $\mathbf{b}$  has:

$$b_{2l} = 0, \text{ where } 1 \leq l < \lfloor \frac{k}{2} \rfloor.$$

## Example

Sparse DSI matrix  $\mathbf{D}_4$  over  $\text{GF}(2^8)$ :

$$\begin{pmatrix} b_1 & 0 & 0 & a_1 \\ a_2 & 0 & 0 & 0 \\ 0 & a_3 & b_3 & 0 \\ 0 & 0 & a_4 & 0 \end{pmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} b_1 a \oplus a_1 d \\ a_2 a \\ a_3 b \oplus b_3 c \\ a_4 c \end{bmatrix}$$

The implementation cost  $\mathcal{C}(\mathbf{D}_4) = \sum \mathcal{C}(a_i) + \sum \mathcal{C}(b_i) + 2 \cdot 8$ .

# Fixed Cost of Sparse DSI matrices

## Corollary

*Sparse DSI matrix of order  $k$  can potentially be  $k$ -MDS.*

Thus, the fixed cost of a  $k$ -MDS sparse DSI matrix of order  $k$  over  $\text{GF}(2^s)$  is

$$\left\lceil \frac{k}{2} \right\rceil \cdot s$$

Matrix type	$k$ -MDS sparse DSI	$k$ -MDS LFS	MDS
Fixed cost	$\left\lceil \frac{k}{2} \right\rceil \cdot s$	$(k-1) \cdot s$	$k \cdot (k-1) \cdot s$



# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

# Circuit of Sparse DSI and LFS Matrices

Expressing the matrices as the following implementation circuits:

$$\begin{pmatrix} b_1 & 0 & 0 & a_1 \\ a_2 & 0 & 0 & 0 \\ 0 & a_3 & b_3 & 0 \\ 0 & 0 & a_4 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ z_0 & z_1 & z_2 & z_3 \end{pmatrix}$$

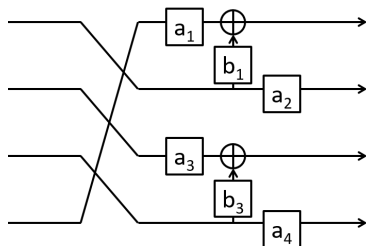


Figure: Sparse DSI

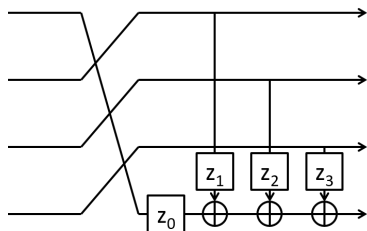


Figure: LFS

# Saving Variable Cost for Sparse DSI Matrices

We can save some variable cost if there are identical coefficients:

$$\begin{pmatrix} b_1 & 0 & 0 & a_1 \\ a_2 & 0 & 0 & 0 \\ 0 & a_3 & b_3 & 0 \\ 0 & 0 & a_4 & 0 \end{pmatrix}$$

Suppose we have  $a_2 = b_1$ , then we can save  $\mathcal{C}(b_1)$ .

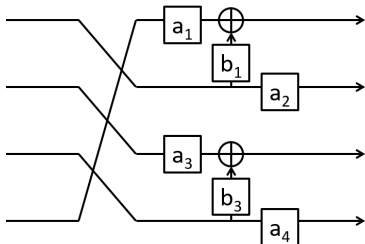


Figure: Sparse DSI

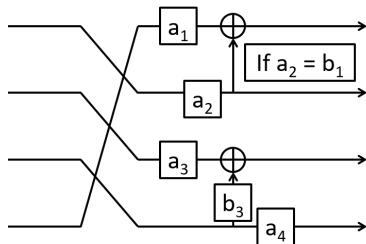


Figure: Sparse DSI saving cost

# Saving Variable Cost for LFS Matrices

Similarly for LFS matrices:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ z_0 & z_1 & z_2 & z_3 \end{pmatrix}$$

Suppose we have  $z_2 = z_1$ , then we can save  $\mathcal{C}(z_2)$ .

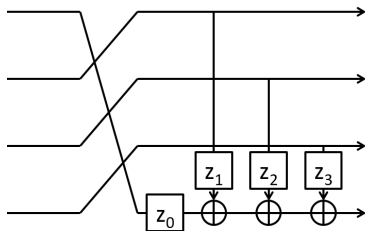


Figure: LFS

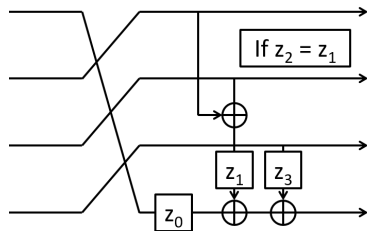


Figure: LFS saving cost

# Total XOR count of various matrices

matrices of order $k$ over $GF(2^s)$	XOR count of the entire matrix
Sparse DSI	$\sum \mathcal{C}(a_i) + \sum_{b_i \neq a_{i+1}} \mathcal{C}(b_i) + \lceil k/2 \rceil \cdot s$
LFS	$\sum_{z_i   \forall j < i, z_i \neq z_j} \mathcal{C}(z_i) + (k - 1) \cdot s$
MDS	$\sum \mathcal{C}(m_i) + k \cdot (k - 1) \cdot s$

where  $m_i$ 's are the entries ( $k^2$  elements) of an MDS matrix.

We also show that the **inverse of DSI and LFS matrices (backward)** has the same implementation cost as the forward direction.

# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

## Comparison of Diffusion Matrices

We found new lightweight sparse DSI and LFS matrices of order 4 to 8 over  $GF(2^4)$  and  $GF(2^8)$ .

Implementation cost of diffusion matrices over  $GF(2^8)$

k	Matrix Type	Forward	Backward	Ref.
4	Circulant	$48 + 4 \cdot 24 = \mathbf{144}$	$212 + 4 \cdot 24 = \mathbf{308}$	AES
4	LFS	$9 + 24 = \mathbf{33}$		[KP+14]
4	8-MDS LFS	$3 + 24 = \mathbf{27}$		[SS+17]
4	Sparse DSI	$6 + 16 = \mathbf{22}$		This Paper
5	IMDS left-circ.	$165 + 5 \cdot 32 = \mathbf{325}$		[LS16]
5	Left-circulant	$50 + 5 \cdot 32 = \mathbf{210}$	$290 + 5 \cdot 32 = \mathbf{450}$	[LS16]
5	Sparse DSI	$7 + 24 = \mathbf{31}$		This Paper
6	LFS $A_{288}$	$17 + 40 = \mathbf{57}$		PHOTON
6	Sparse DSI	$7 + 24 = \mathbf{31}$		This Paper



# Table of Contents

- 1 Introduction
- 2 Serial-type Matrices
  - LFS Matrices
  - DSI and Sparse DSI Matrices
- 3 New Lightweight Diffusion Matrices
  - Evaluating the Implementation Cost of Serial-type Matrices
  - Some Results
- 4 Optimal Serial-type Matrix of Order 4

## Trade-off for Diffusion Matrices

In comparison with MDS diffusion matrices of order  $k$ ,  $k$ -MDS LFS matrices have a fair trade-off between the area and clock cycle.

$$\begin{array}{ccc} \text{MDS} & \xrightarrow{1 \uparrow k \text{ clock cycles}} & k\text{-MDS} \\ \text{matrix} & k \cdot (k-1) \downarrow (k-1) \text{ s-bit XORs} & \text{LFS matrix} \end{array}$$

Our  $k$ -MDS sparse DSI (sDSI) matrices **achieve a trade surplus**.

$$\begin{array}{ccc} \text{MDS} & \xrightarrow{1 \uparrow k \text{ clock cycles}} & k\text{-MDS} \\ \text{matrix} & k \cdot (k-1) \downarrow \left\lceil \frac{k}{2} \right\rceil \text{ s-bit XORs} & \text{sDSI matrix} \end{array}$$

A natural question to ask:

Can we achieve even lower fixed cost?

We look at **diffusion matrices of order 4**.

## OXS Matrix of Order 4

Sparse DSI matrix has 2  $s$ -bit XORs, thus we consider matrix with only 1  $s$ -bit XOR, so-called One XOR Serial (OXS) matrix.

$$\begin{array}{ccc}
 4\text{-MDS} & \xrightarrow{4 \uparrow \leq 8 \text{ clock cycles}} & q\text{-MDS} \\
 \text{sDSI matrix} & \xrightarrow{2 \downarrow 1 \text{ } s\text{-bit XORs}} & \text{OXS matrix}
 \end{array}$$

We consider  $q \leq 8$ , otherwise it is a bad trade-off.

### Theorem

*There does not exist OXS matrix of order 4 that is  $q$ -MDS, where  $q \leq 8$ .*

Therefore, we conclude that our **sparse DSI matrix of order 4 has the minimal fixed cost.**

## Conclusion

- Introduce a new serial-type matrix called Diagonal-Serial Invertible (DSI) matrix with sparse property
- $k$ -MDS sparse DSI matrix has a positive trade-off between the hardware area and clock cycle
- Found new lightweight serial-type matrices
- Prove that our sparse DSI matrix of order 4 has the minimal fixed cost

## Reference

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Thank you. :)